

## **Depth Perception**

### Deep Blue See



#### Overview

- ➤ Cue Theory
- Monocular Cues
- ➤ Binocular Cues
- ➤ Neural Basis
- ➤ Interaction of Cues



## **Cue Theory**

- ➤ We learn to associate a cue (or retinal or image element) with our experience of depth in the environment
- > Types of cues:
  - Oculomotor
  - Monocular
  - Binocular



### **Oculomotor Cues**

### Convergence

- Inward movement of the eyes
- Required to keep image on fovea
- Muscular (afferent) signal cues distance
- More convergence = closer object

#### Accommodation

- Change in shape of the lens
- Required to keep objects at different distances in focus
- Afferent signal

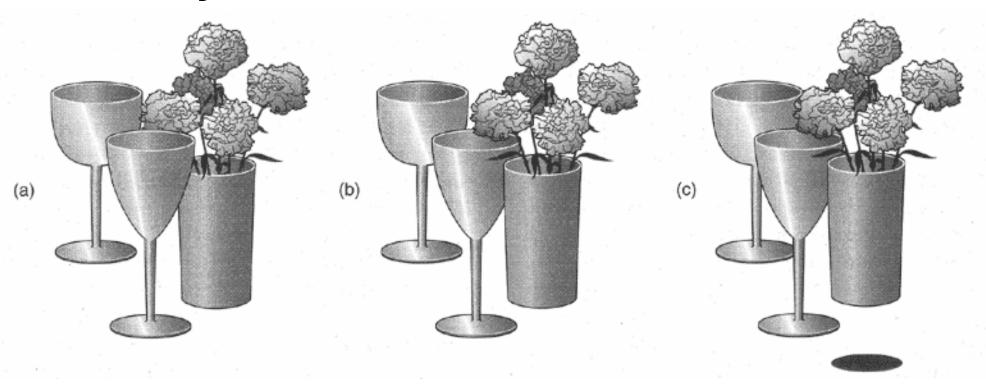


### **Monocular Cues**

- Using information provided by only one eye (or at least not requiring two eyes) leads to many reliable depth cues
- Some are mechanical/muscular/bottom up
- Some require top-down processing
- > Learning plays a major role in all depth cues



➤ One object hides another, it must be nearer















April



## Relative vertical position

- Location in a frame
- ➤ Higher is usually farther

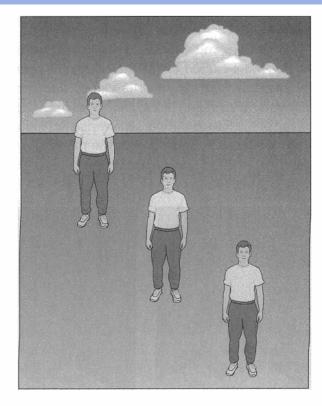


Figure 7.4
Relative height. Other things being equal, objects below the horizon that appear higher in the field of view are seen as being farther away. Objects above the horizon that appear lower in the field of view are seen as being farther away.







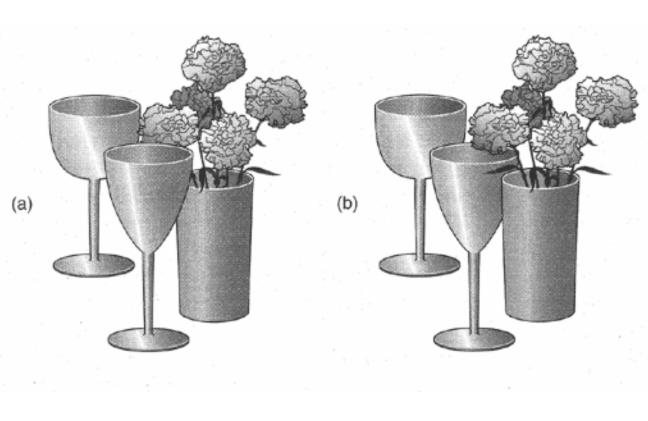
## Relative vertical position

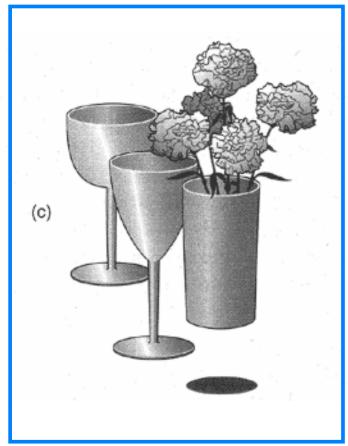




### **Shadows**

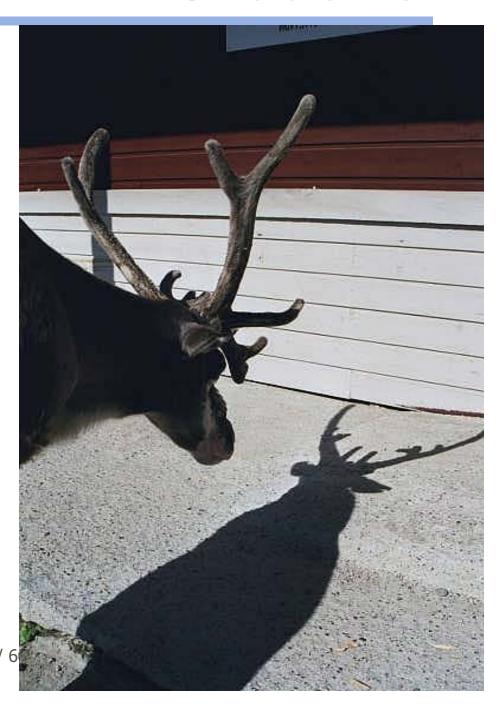
Where an object casts a shadow can determine its distance (and height)





## **Shadows**

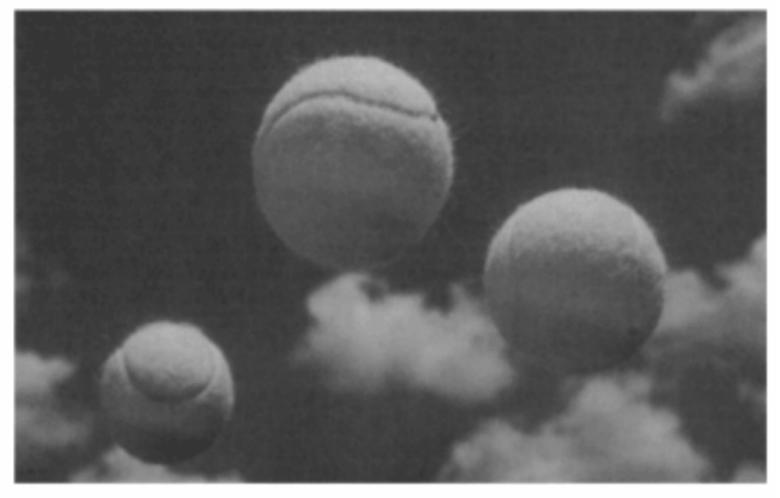




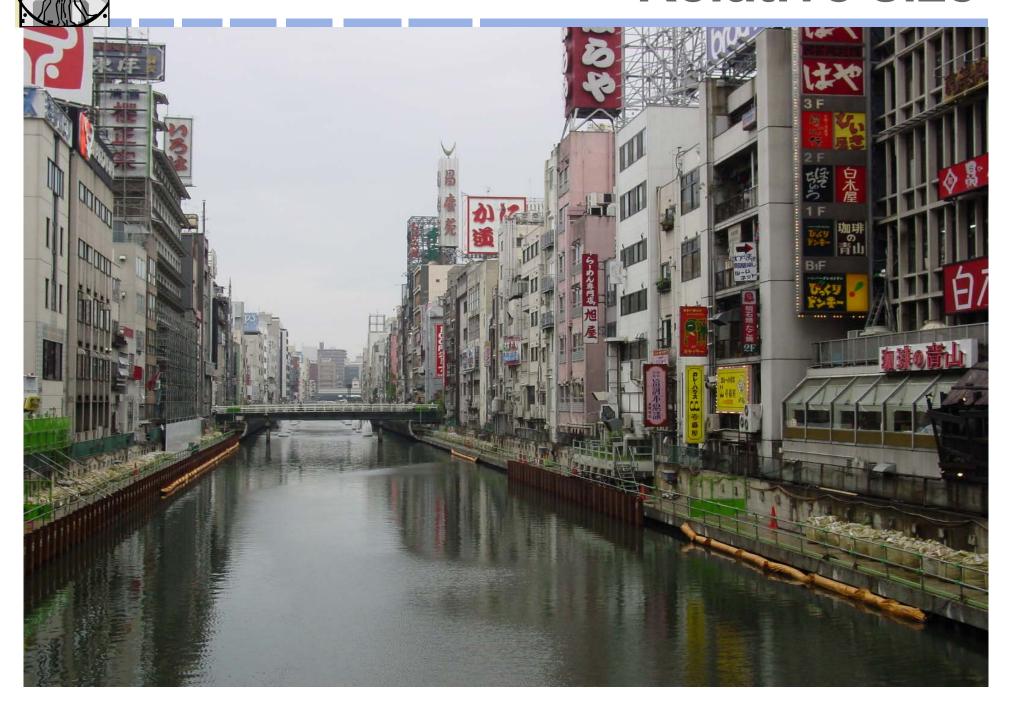


### Relative size

Smaller retinal image for same size object means the object is farther away



### **Relative size**



### **Relative size**





April 5, 2020

PS



## Familiar (template) size

Knowledge of actual size differences can affect how we interpret relative distances





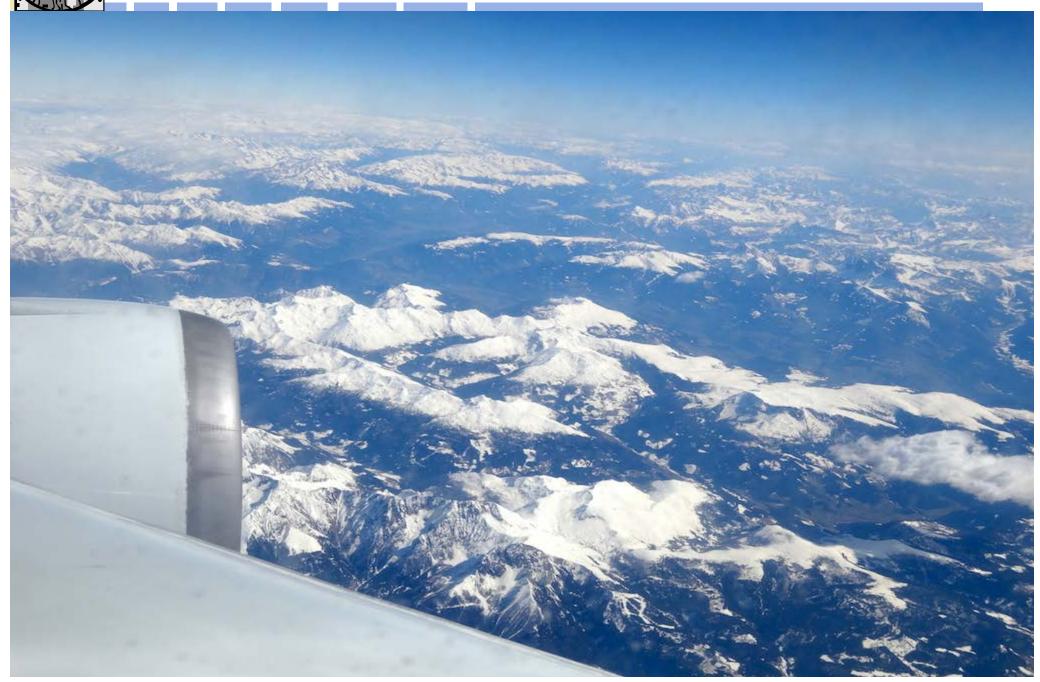


## **Atmospheric perspective**

Distant objects appear blurry, and also more blue, due to Rayleigh scattering

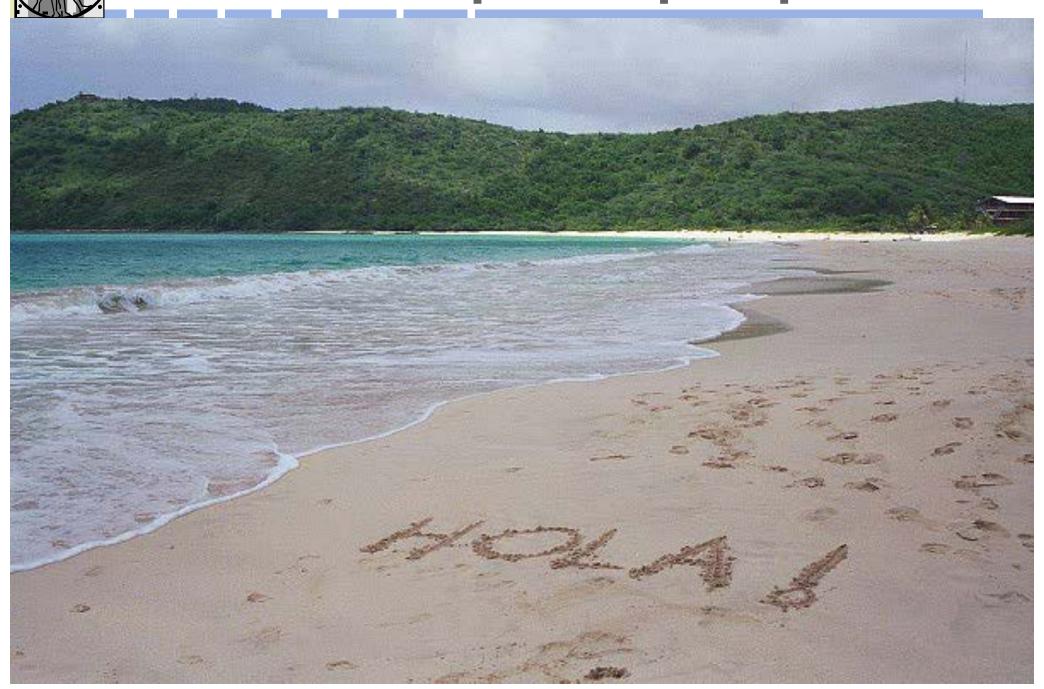


# Atmospheric perspective





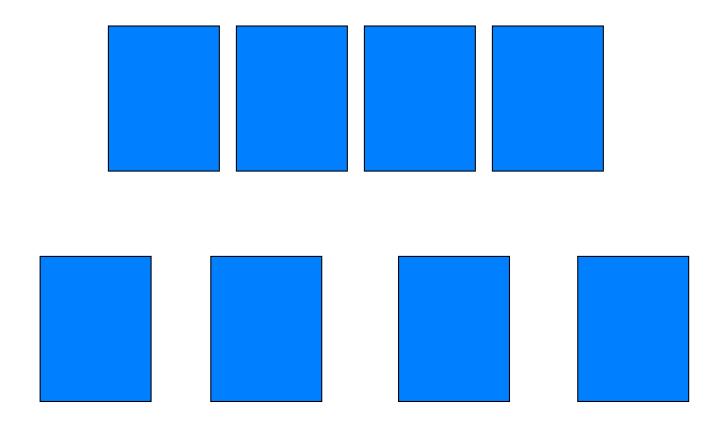
# **Atmospheric perspective**



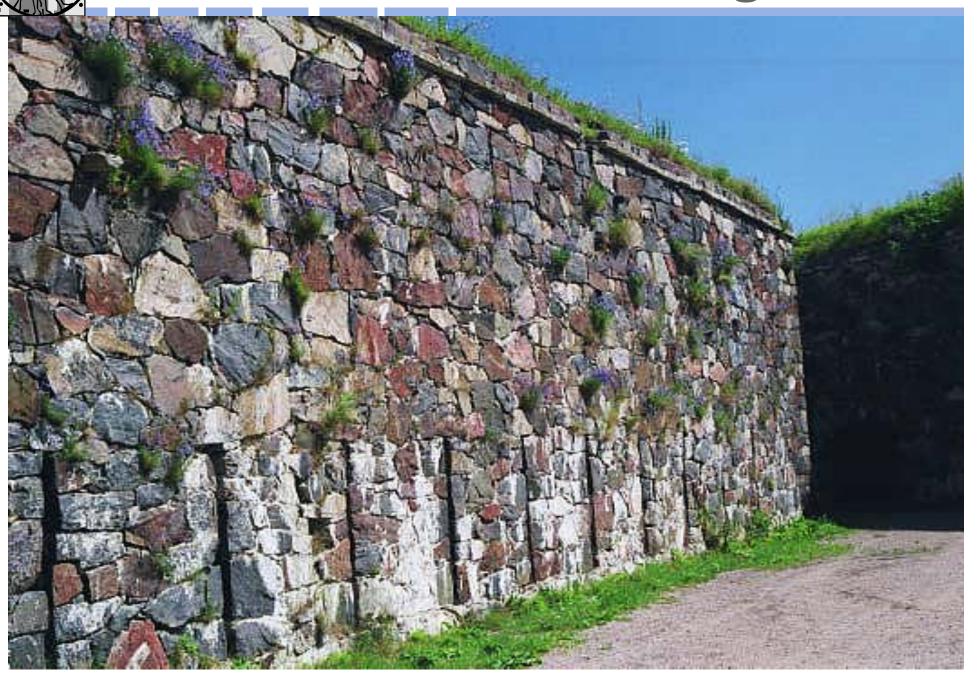


## Texture gradient

Evenly spaced items appear more closely packed in the distance

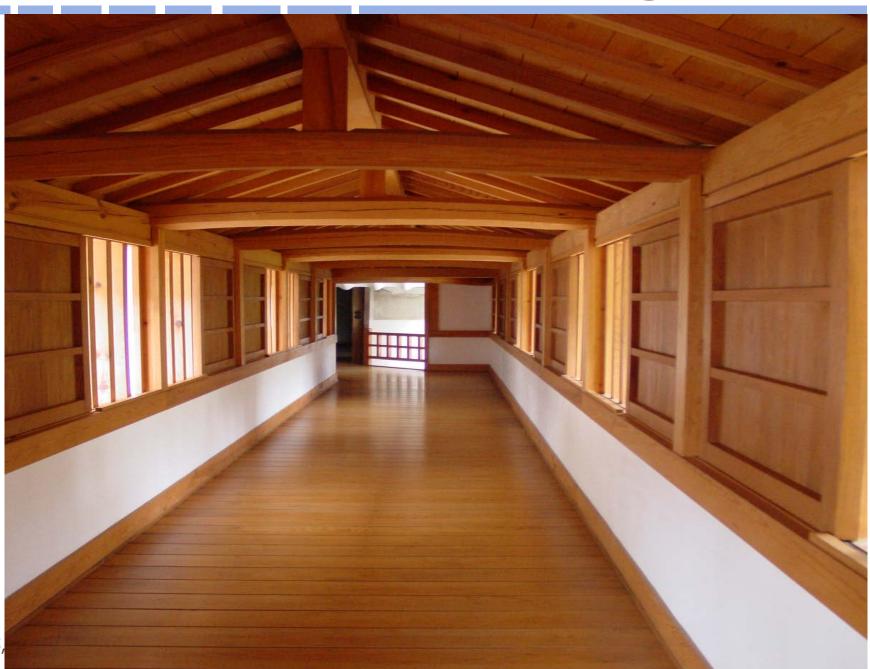








## **Texture gradient**





### **Gradients and Texture?**





## Highlight cues

- Areas of light (or dark) signal depth of objects
- Similar to shadows cueing interposition



## Highlight cues

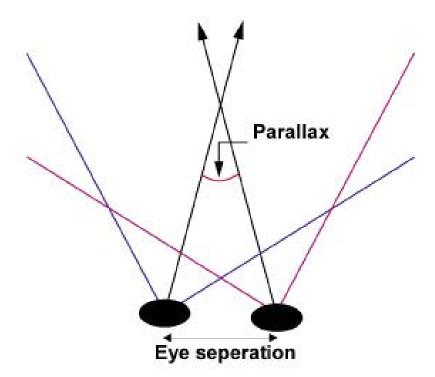






#### Parallax

- Changes in movement speed due to distance
- Closer objects move faster
- > Farther objects move slower



## **Parallax**







## Deletion/accretion (occlusion)

Objects that appear and take the place of objects previously in the scene must be moving in front of the original objects



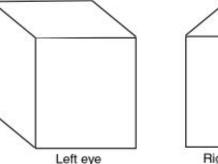
## Deletion/accretion (occlusion)

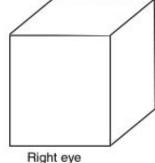




### **Binocular Cues**

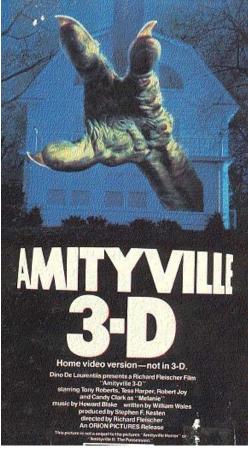
- Convergence of eyes
  - Both oculomotor and retinal cues come from convergence
- Binocular disparity
  - Difference in the image seen in the left and right eye
  - A retinal effect
  - Disparity leads to stereopsis
  - Separation can be done by
    - Physically separate images presented
    - Different colored images
    - Polarization





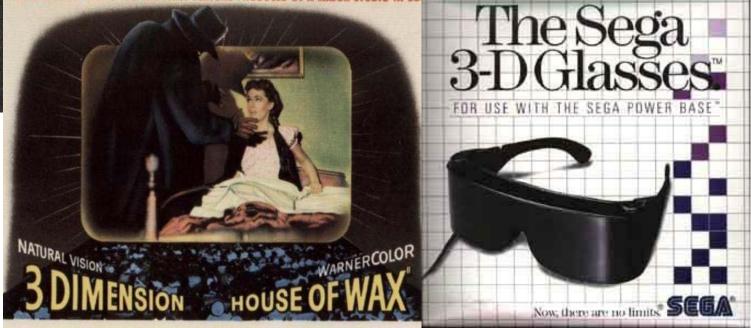


### **Stereo Vision**





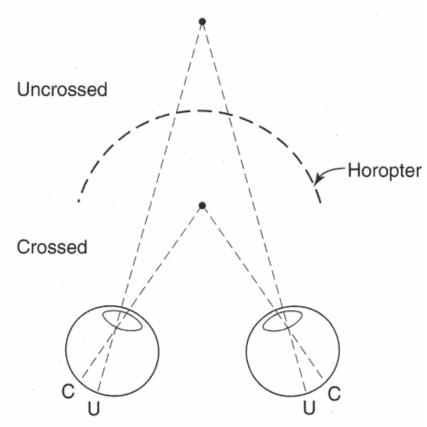






## Binocular Disparity, cont' d

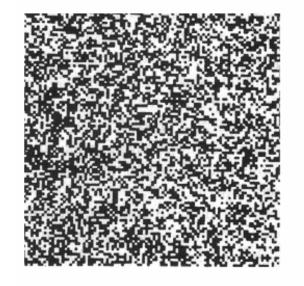
- Horopter
  - From horizon + optical
  - All points on this line (surface)
     are same distance as objects at
     fixation
- Computation of depth from disparity
  - Direction (laterally/nasally) of disparity determines if object is in front of or behind the horopter
  - Amount of disparity determines distance from the horopter

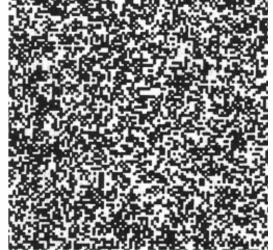


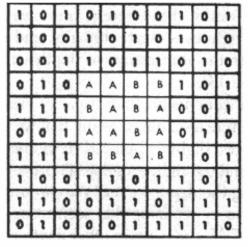


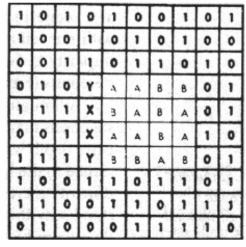
## Random dot stereogram

- ➤ Only disparity information is available
  - Therefore purely bottom-up





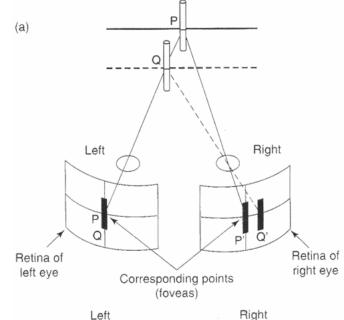


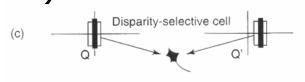




## eural Basis of Depth Perception

- Disparity detectors in striate cortex (V1)
  - Fixation plane
    - No disparity
  - "nearer" detectors
    - Crossed disparity
  - "farther" detectors
    - Uncrossed disparity
  - Detection circuits also present in:
    - dorsal (where/how) pathway (V2, MT)
    - ventral (what) pathway





Zero disparity cell



## Neural Basis, cont' d

#### > Stereoblindness

- Cannot detect/localize the depth of objects using disparity at all
  - Other monocular cues can still be used
- Partial stereoblindness: cannot detect depth of objects that are either at, in front, or behind horopter
  - Evidence for 3 sets of disparity detectors



## **Development of Stereopsis**

- Binocular input required early in life to develop stereo vision
- ➤ Infants whose eyes are not focused on same point (crossed or lazy eyes) may not develop proper stereopsis
  - Even if eye condition is later fixed (surgically)
- ➤ Critical period: ~1-3 years
- What does this imply about locus of stereo vision?



### Interaction of cues

- ➤ Thoughts...
  - There are lots of cues, both monocular and binocular. How do they interact?
  - How does depth perception develop/evolve?
  - Can one eye work well?

	0-2 meters 2.30 meters	30 1112
Depth information	O. S. Br	
Occlusion		
Relative size		
Accommodation and convergence		
Motion		
Disparity		
Height		
Atmospheric perspective		



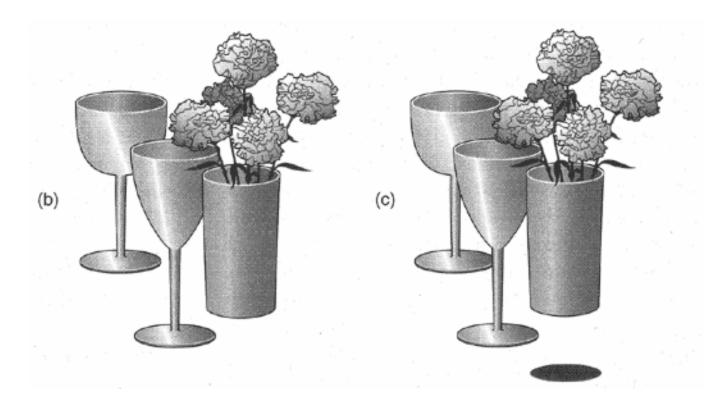
## Interaction of Cues, cont'd

- Constructivist approach
  - Experience enables inferences about distances and spatial layout
  - We "construct" our environment (mentally) based on images and cues
  - Somewhat computational
- > Gibson's Direct Perception approach
  - Spatial layout is directly picked up not the result of analysis or computation
  - Too bottom-up?



### One Cue vs. Another?

- How can we determine if/when one cue will override another?
  - Recall shadow and shading on vase

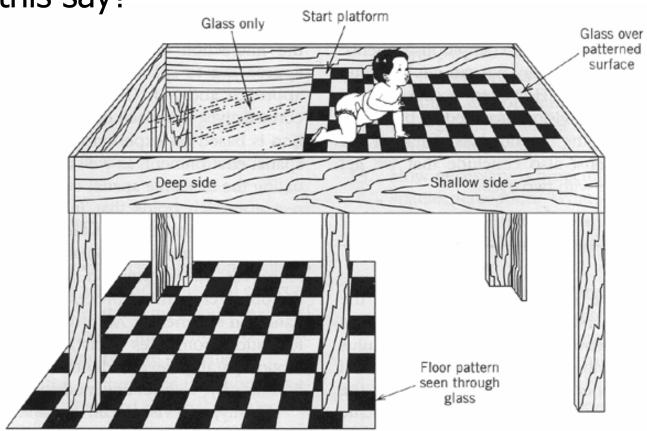




### **Visual Cliff**

- > Test to see which visual cues dominate
  - Parallax seemed to be only dominant cue
  - Note: Monocular cue

What does this say?





## **Upcoming**

- ➤ Constancy & illusions
- ➤ Camouflage